

# Regularity of solutions to Hamilton-Jacobi and Hyperbolic Conservation Laws

L. Caravenna, C. De Lellis, M. Gloyer, R. Robyr, S. B.

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## Introduction

What kind of regularity

Precise statements

Related problems

## Transport along rays

Area estimate

Disintegration

Reformulation of transport equation

## SBV estimates for HJ and HCL

A formula for the divergence

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Consider the Hamilton-Jacobi equation

$$u_t + H(\nabla u) = 0, \quad (t, x) \in \mathbb{R}^+ \times \mathbb{R}^m,$$

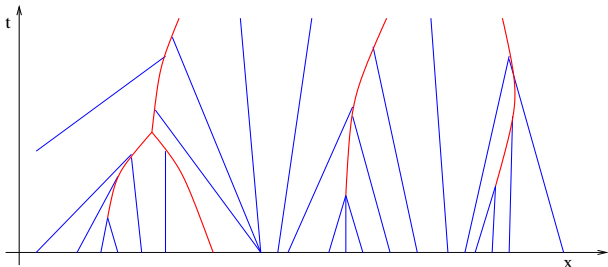
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with uniformly convex Hamiltonian  $H$  and Lipschitz initial data. We expect a smooth function outside countably many regular hypersurfaces of codimension 1.



# Structure of solutions to Hamilton-Jacobi

For strictly hyperbolic system of conservation laws in one space dimension

$$u_t + f(u)_x = 0, \quad (t, x) \in \mathbb{R}^+ \times \mathbb{R}, \quad u \in \mathbb{R}^n,$$

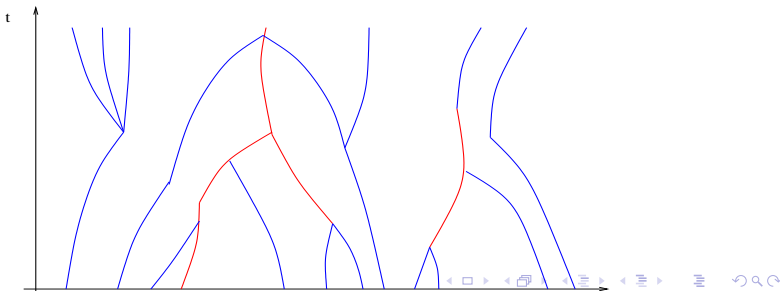
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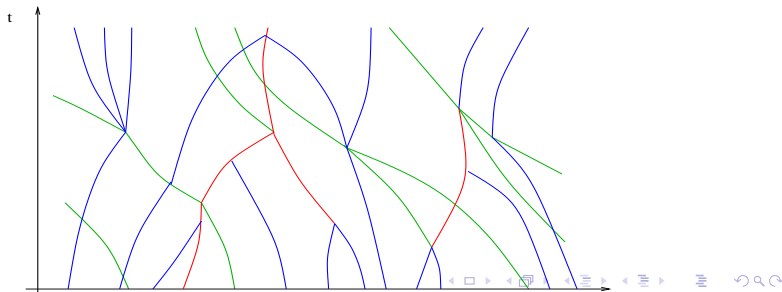


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The first question is an easy application of a well known rectifiability criteria.

# Euler-Lagrange equation for singular variational problems

The Euler-Lagrange equation for the functional

$$\int_{\Omega} (\mathbf{I}_D(\nabla u) + u) \mathcal{L}^m, \quad u \in u_0 + W_0^{1,\infty}(\Omega),$$

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where  $d$  is the direction of the optimal ray for the viscosity solution

$$1 - (\mathbf{I}_D)^*(\nabla u) = 0, \quad u|_{\partial\Omega} = u_0.$$



# Optimal transportation

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can be written as transportation problems along a set of geodesic, and the dynamical interpretation of the transport correspond to solve the PDE (in the sense of currents)

$$\operatorname{div}(d\rho) = \mu - \nu,$$

where  $d$  is the “direction” of the geodesics.

## Precise decay estimates

The derivative of a solution a gnl system of conservation laws can be decomposed in waves

$$u_x = \sum_i v_i \tilde{r}_i, \quad u_t = \sum_i w_i \tilde{r}_i,$$

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## Area estimate

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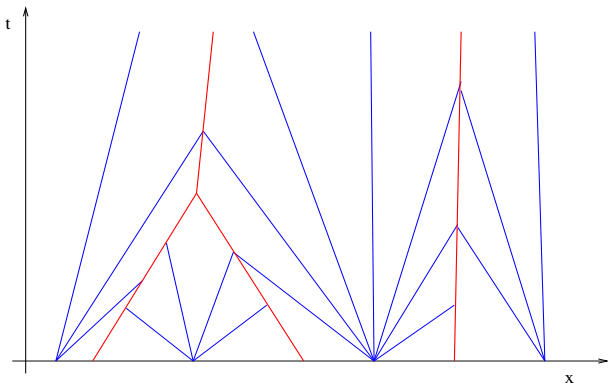
is given by

$$u(t, x) = \min \left\{ u(0, y) + tL\left(\frac{x - y}{t}\right) \right\}, \quad L = H^*.$$

In particular, it is uniformly approximated by the sequence of functions

$$u_n(t, x) = \min \left\{ u(0, y) + tL\left(\frac{x - y}{t}\right), y \in \{y_1, \dots, y_n\} \right\}. \quad (1)$$

These solutions have a very simple structure:



In particular, we have the estimates:

1. divergence is a measure

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By (1), one can show that this is the worst case, i.e.

$$c(t, s, x) \begin{cases} \leq \left( \frac{t-s}{t} \right)^m & t \leq s \\ \geq \left( \frac{t-s}{t} \right)^m & t \geq s \end{cases}$$

Since along optimal rays we have the dual solution

$$u(s, x) = \max \left\{ u(t, y) - (t - s)L\left(\frac{y - x}{t - s}\right) \right\},$$

we obtain the bound on the Jacobian

$$\min \left\{ \left(\frac{t - s}{t}\right)^m, \left(\frac{T - s}{T - t}\right)^m \right\} \leq c \leq \max \left\{ \left(\frac{t - s}{t}\right)^m, \left(\frac{T - s}{T - t}\right)^m \right\},$$

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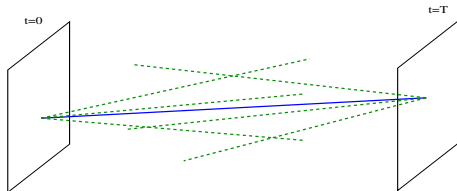
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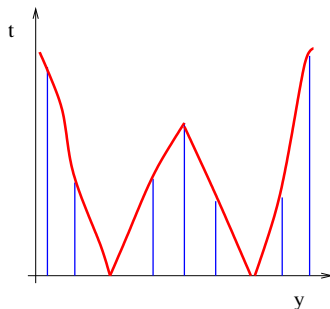
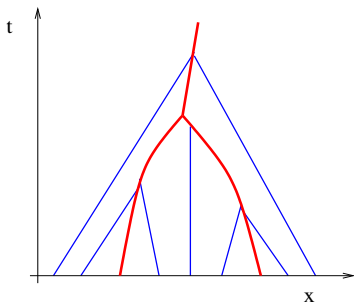


# Disintegration of Lebesgue measure

The above estimate implies that the change of variable

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$$\mathcal{L}_{\mathbb{R}^+ \times \mathbb{R}^m}^{d+1} = \int c(t, y) dt m(dy),$$

i.e.  $\forall \phi \in C^c(\mathbb{R}^+ \times \mathbb{R}^m)$

$$\int \phi \mathcal{L}^{d+1} = \int \left( \int \phi(t, y + td(y)) c(t, y) dt \right) m(dy).$$

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**Remark.** The proof depends only on the convexity of  $H$ .



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- A formula for the divergence

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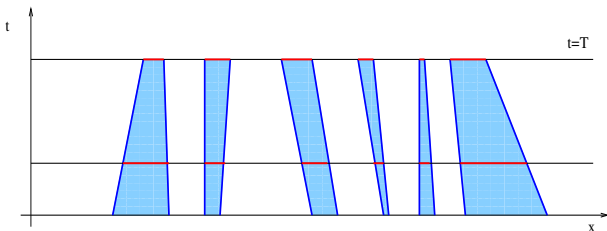
In the case of uniform convexity, it is possible to prove the following formula: if  $A$  is a set where  $d$  is single valued, then for  $t > 0$

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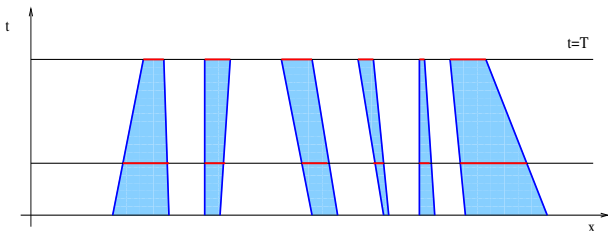
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In particular, if there is a Cantor part (hence single rays), the area is strictly positive.

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Since  $d(t, x) = D^2 H(\nabla u) D^2 u$ , we obtain that  $\text{tr}(D^2 u)$  has not Cantor parts, hence  $D^2 u$  has not Cantor parts.

## A measure for shock creation

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$$(v_i^s)_t + (\tilde{\lambda}_i v_i^s)_x = J_i^s,$$

$$|J_i^s|((s, t] \times \mathbb{R}) \leq \text{Tot. Var.}(v_v - v_i^s(s)) - \text{Tot. Var.}(v_v - v_i^s(t)) \\ + C(Q(s) - Q(t)).$$

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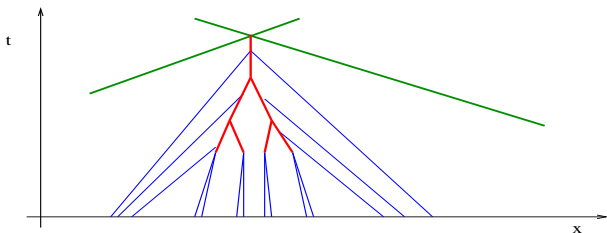
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The continuous part  $v_i^c$  of  $v_i$  thus satisfies

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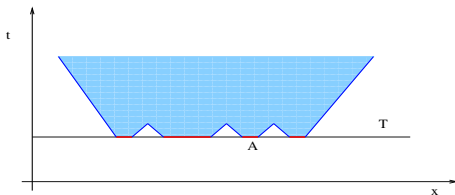
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