

Decomposition of vector fields in \mathbb{R}^d

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Continuity equation and ODEs

The smooth case

Relation among ODE and PDE

Renormalization

Directional regularity and uniqueness

Regular Lagrangian flows

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Estimate on the regularity

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Regularity for Lagrangian representations

A basic PDEs

In many systems of PDEs one of the equations is the *continuity equation*

$$\partial_t \rho + \operatorname{div}(\rho \mathbf{b}) = \partial_t \rho + \sum_{i=1}^d \partial_{x_i}(\rho b_i) = 0.$$

This equation means that the quantity ρ is conserved: in every regular region Ω

$$\frac{d}{dt} \int_{\Omega} \rho = \int_{\partial\Omega} \rho \mathbf{b} \cdot \mathbf{n},$$

or equivalently in weak form

$$\int \rho(\partial_t \psi + \mathbf{b} \cdot \nabla \psi) dx dt + \int \rho \psi(t=0) dx = 0$$

for every smooth test function ψ .

There is a clear relation with the ODE

$$\frac{d}{dt}X(t, y) = \mathbf{b}(t, X(t, y)), \quad X(0, y) = y.$$

Indeed the function given by

$$\int_{\Omega} \rho(t, x) = \int_{X^{-1}(\Omega)} \rho_0(y) dy$$

is a solution to the continuity equation: just observe that if

$$\Omega(t) = \{X(t, y), y \in \Omega(0)\}$$

then the lateral flow in 0.

Classical PDEs

One is usually interested in solving the ODE

$$\frac{d}{dt}X(t, y) = \mathbf{b}(t, X(t, y)), \quad X(0, y) = y.$$

for every initial point y .

If \mathbf{b} is continuous, then Peano's theorem yields an existence result: there exists at least one solution for every initial datum.

If we ask more regularity w.r.t. x , e.g.

$$|\mathbf{b}(t, x) - \mathbf{b}(t, x')| \leq C|x - x'|,$$

then one has also uniqueness.

For such sufficiently regular vector fields, one has thus existence and (in case) uniqueness for the solution of the continuity equation: indeed one can rewrite the PDE as

$$\partial_t(\rho(t, X(t, y)) \det \nabla_y X(t, y)) = 0.$$

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On the other hand, a weak solution to

$$\partial_t \rho + \operatorname{div}(\rho \mathbf{b}) = 0,$$

requires only $\rho, \rho \mathbf{b}$ to be locally integrable: for ψ smooth

$$\int \rho(\partial_t \psi + \mathbf{b} \cdot \nabla \psi) dx dt + \int \rho \psi(t=0) dx = 0.$$

The vector field \mathbf{b} is determined by the solution to a system of PDEs, but in general it is not smooth; in the following we will unlink this dependence of \mathbf{b} and look for an almost everywhere well posedness of the Cauchy problem for the ODE.

Lagrangian representation

Consider the PDE for $\rho \geq 0$

$$\partial_t \rho + \operatorname{div}(\rho \mathbf{b}) = \mu^+ - \mu^-, \quad \mu^\pm \text{ locally bounded measures.}$$

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Theorem (Smirnov, Ambrosio)

There exists a measure η on the space

$$\Gamma = \left\{ \gamma : [t_\gamma^-, t_\gamma^+] \rightarrow \mathbb{R}^d, \frac{d\gamma}{dt} = \mathbf{b}(t, \gamma) \right\}$$

such that

$$\int \psi \rho(1, \mathbf{b}) dx dt = \int \left\{ \int_{t_\gamma^-}^{t_\gamma^+} \psi(t, \gamma(t)) \left(1, \frac{d\gamma}{dt} \right) dt \right\} \eta(d\gamma),$$

$$\int \phi \mu^\pm(dtdx) = \int \psi(t_\gamma^\mp, \gamma(t_\gamma^\mp)) \eta(d\gamma).$$

Some remark:

- ▶ the existence of such a measure can be interpreted as the fact that if we have a solution to the PDE then there are enough solutions to the ODE to represent it;
- ▶ it holds also for $\rho, \rho \mathbf{b}$ measures;
- ▶ the uniqueness of η is lost for two reasons:
 1. the trajectories cross each other,
 2. one can exchange initial and final points between trajectories.

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- ▶ the uniqueness of η is lost for two reasons:
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The nonuniqueness is thus related to the first situation: we say that η is *untangled* if it is concentrated on a set of trajectories \mathcal{I} such that

$$\gamma, \gamma' \in \mathcal{I} \text{ intersecting} \iff \gamma \cup \gamma' \text{ still a trajectory.}$$

A "classical" approach

($\mu^\pm = 0$ for simplicity.) One can give a meaning to

$$\partial_t u + \mathbf{b} \cdot \nabla u = 0, \quad u(t = 0) = u_0, \quad (1)$$

by requiring that

$$\partial_t(\rho u) + \operatorname{div}(\rho u \mathbf{b}) = 0, \quad \rho u(t = 0) = \rho_0 u_0. \quad (2)$$

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The chain rule in the classical sense given that if u is a solution then also $\beta(u)$ is a solution to (1) for β smooth: indeed $u(t, \gamma(t))$ is constant.

In the literature such a property

$$\forall u \in L^\infty(\rho) \left(\rho u \text{ solution to (2)} \implies \rho \beta(u) \text{ is a solution to (2)} \right)$$

is called *renormalization property* (of $\rho(\mathbf{1}, \mathbf{b})$).

If every solution ρ enjoys the renormalization property, then uniqueness for every initial data:

- ▶ if for some initial point x_0 one has two solutions $\gamma_1 \neq \gamma_2$, $\gamma_1(0) = \gamma_2(0) = x_0$, then take

$$\rho(t) = \frac{1}{2}(\delta_{\gamma_1(t)} + \delta_{\gamma_2(t)}), \quad \rho u(t) = \frac{1}{2}(\delta_{\gamma_1(t)} - \delta_{\gamma_2(t)})$$

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- ▶ if uniqueness for every initial data, then

$$\rho(t) = \int \delta_{\gamma(t)} \rho_0(d\gamma(0)), \quad \rho u(t) = \int \delta_{\gamma(t)} \rho_0 u_0(d\gamma(0)),$$

so that u is constant along the trajectories used by ρ .

In general one relaxes this condition requiring ρ to belong to some class, e.g.

$$0 \leq \rho \leq C.$$

In this case one obtains that

renormalization property for all $\rho \leq C$



uniqueness among *regular Lagrangian flows*.

Regular Lagrangian flows $X(t, x)$ are such that

$$\frac{d}{dt}X = \mathbf{b}(t, X), \quad X(t)^{-1}(\Omega) \leq C\mathcal{L}^d(\Omega).$$

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Remark. We are not saying that for almost every initial data x_0 there exists a unique solution to the ODE (OPEN).

Key computation [Diperna-Lions]: ($\rho = 1$ and $\operatorname{div} \mathbf{b} = 0$) if $u^\epsilon = \phi^\epsilon * u$ is a smoothing of u , then one computes

$$\partial_t \beta(u^\epsilon) + \mathbf{b} \cdot \nabla \beta(u^\epsilon) = \beta'(u^\epsilon) (\mathbf{b} \cdot \nabla u^\epsilon - (\mathbf{b} \cdot \nabla u)^\epsilon),$$

and thus the problem reduces in showing that as $\epsilon \rightarrow 0$ the commutator

$$\mathbf{b} \cdot \nabla u^\epsilon - (\mathbf{b} \cdot \nabla u)^\epsilon = \int u(x + \epsilon y) \frac{\mathbf{b}(x) - \mathbf{b}(x + \epsilon y)}{\epsilon} \cdot \nabla \phi(y) dy \rightarrow 0.$$

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If $\nabla b \in L^1$ then this can be done, otherwise the convergence of the integrand is not strong enough to pass to the limit.

Remark. It seems that \mathbf{b} should have some sort of weak derivative...

Keyfitz-Kranzer system

The system of conservation laws

$$\partial_t u + \sum_i \partial_{x_i} (f_i(|u|)u) = 0, \quad u \in \mathbb{R}^m,$$

can be written as

$$\partial_t |u| + \operatorname{div}(\mathbf{f}(|u|)|u|) = 0, \quad \partial_t \theta + \mathbf{f}(|u|) \cdot \nabla \theta = 0,$$

where $\theta = u/|u|$.

The theory of Kruzhkov yields for scalar conservation laws that $\nabla |u|$ is a bounded measure, and thus one reduces to a transport equation with vector fields whose derivative is a measure.

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1. if $\operatorname{div} \mathbf{b}$ is an L^1 function, one needs to change the convolution kernel ϕ : by adapting to the local structure of \mathbf{b} (Rank-One Theorem), still the commutator converges to 0 (weakly, [Ambrosio])

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3. in the so called Cantor part, no clear choice of ϕ and no trace theory.

A regularity approach

In the smooth case one has

$$\frac{d}{dt} \nabla X = \nabla \mathbf{b}(t, X) \nabla X,$$

so that

$$\frac{d}{dt} \log \nabla X = \nabla \mathbf{b}, \quad \nabla X = \exp \left\{ \int \nabla \mathbf{b} dt \right\}.$$

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Unfortunately \log is sublinear, so that no compactness estimate can be obtained, but one can hope to have an estimate for

$$A_r(t, x) = \frac{1}{r^d} \int_{|y| < r} \log \left(1 + \frac{|X(t, x+y) - X(t, x)|}{r} \right) dy.$$

[DeLellis-Crippa] Indeed

$$\begin{aligned} \frac{d}{dt} A_r &\leq \frac{1}{r^d} \int_{|y|<r} \frac{|\mathbf{b}(t, x+y) - \mathbf{b}(t, x)|}{|y|} dy \\ &\leq M_{\nabla \mathbf{b}}(x) + M_{M_{\nabla \mathbf{b}}}(x), \end{aligned}$$

being the maximal function M

$$M_f(x) = \sup_r \frac{1}{r^d} \int_{|y|<r} |f|(x+y) dy.$$

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If $\nabla \mathbf{b} \in L^p$, $p > 1$, then

$$\int \sup_r A_r(t, x) dx \leq C_0 + C_1 \int_0^t \|\nabla \mathbf{b}\|_{L^p} dt.$$

In particular, if at time T we have a mixing of order δ , i.e. it means that a constant fraction of trajectories starting from T at a distance $< \delta$ are then separated by 1, so that (inverting time)

$$\int \sup_r A_r(0, x) dx \simeq \log(1 + 1/\delta) \leq C_0 + C_1 \int_0^t \|\nabla \mathbf{b}\|_{L^p} dt.$$

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Bressan Mixing Conjecture: if the vector fields \mathbf{b} mixes $\rho \in [1/C, C]$ to order δ at time $T = 1$, then

$$\int_0^1 |\nabla \mathbf{b}| dx dt \geq C \log \delta^{-1}.$$

This is an explicit estimate on compactness.

A way of restating uniqueness

The classical uniqueness/continuity can be written as

$$\forall R > 0 \exists r \left(|\gamma'(0) - \gamma(0)| < r \implies |\gamma'(t) - \gamma(t)| \leq R \right).$$

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In the language of Lagrangian representations η we could write: for all $R, \varpi > 0$ there exists r such that

$$\int \frac{\eta(\{|\gamma'(0) - \gamma(0)| < r, \sup_t |\gamma'(t) - \gamma(t)| > R\})}{\eta(\{|\gamma'(0) - \gamma(0)| < r\})} \eta(d\gamma) < \varpi.$$

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Theorem

The above condition implies untangling of trajectories, hence uniqueness.

In Bressan's case, i.e. when $\nabla \mathbf{b}$ is a measure, one considers the PDE

$$\partial_t 1 + \operatorname{div}(\mathbf{1} \cdot \mathbf{b}) = \operatorname{div} \mathbf{b}.$$

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A consequence of this fact is that the Lagrangian representation η of $(1, \mathbf{b})$ is unique up to the degeneracy of the initial/final points of the curves.

Sorry for the people not cited here and

THANK YOU!